

On Good Matrices and Skew Hadamard Matrices

Gene Awyzio and Jennifer Seberry

Dedicated to Hadi Kharighani on his 70th Birthday

In her PhD thesis (Seberry) Wallis described a method using a variation of the Williamson array to find suitable matrices, which we will call good matrices, to construct skew Hadamard matrices. Good matrices were designed to plug into the Seberry-Williamson array to give skew-Hadamard matrices. We investigate the properties of good matrices in an effort to find a new, efficient, method to compute these matrices. We give the parameters of the supplementary difference sets (sds) which give good matrices for use in the Seberry-Williamson array.

1 Introduction

Many constructions for ± 1 matrices and similar matrices such as Hadamard matrices, weighing matrices, conference matrices and D -optimal designs use skew Hadamard matrices in their construction. For more details see Seberry and Yamada [23].

An Hadamard matrix is a square matrix with elements of ± 1 and mutually orthogonal rows. Thus a $4w \times 4w$ Hadamard matrix must have $2w(4w - 1)$ entries of -1 and $2w(4w + 1)$ entries of $+1$ for a normalized Hadamard matrix, that is one where the first row and first column are all $+1$. For any Hadamard matrix H of size $4w \times 4w$ $HH^T = 4wI_{4w} = H^T H$. In all our examples minus (“ $-$ ”) is used to denote minus one (“ -1 ”).

Gene Awyzio
Faculty of Engineering and Information Sciences, University of Wollongong, NSW, 2522
Australia, e-mail: gene_awyzio@uow.edu.au

Jennifer Seberry
Centre for Computer and Information Security Research,
Faculty of Engineering and Information Sciences, University of Wollongong, NSW, 2522 Australia
e-mail: jennifer_seberry@uow.edu.au

Hadamard matrices of order $4w$ are conjectured to exist for all orders $4w \equiv 0 \pmod{4}$. A weighing matrix, $W = W(4w, k)$, of order $4w$ and weight k has elements $0, \pm 1$ and satisfies $WW^\top = kI_{4w}$. These are conjectured to exist for all $k = 1 \dots 4w$ for each order $4w$. If an Hadamard matrix M , can be written in the form $M = I + S$ where $S^\top = -S$, then M is said to be a *skew-Hadamard matrix*. Skew-Hadamard matrices are also conjectured to exist for all orders $4w \equiv 0 \pmod{4}$. The first unresolved case for Hadamard matrices is currently 4×167 .

Example 1. Hadamard matrices

$$H_2 = \begin{bmatrix} 1 & 1 \\ 1 & - \end{bmatrix} \quad H_{A_{\text{symmetric}}} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & - & - \\ 1 & - & 1 & - \\ 1 & - & - & 1 \end{bmatrix} \quad H_{A_{\text{skew-type}}} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ - & 1 & 1 & - \\ - & - & 1 & 1 \\ - & 1 & - & 1 \end{bmatrix}.$$

1.1 Circulant and Type 1 Matrix Basics

Because it is so important for the rest of our work we now spend a little effort to establish why the properties required for Williamson matrices are so important.

We define the *shift matrix*, T of order n by

$$T = \begin{bmatrix} 0 & 1 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & & & \vdots \\ 1 & 0 & \dots & 0 \end{bmatrix}.$$

So any circulant matrix, of order n and first row x_1, x_2, \dots, x_n , that is,

$$\begin{bmatrix} x_1 & x_2 & x_3 & \dots & x_n \\ x_n & x_1 & x_2 & \dots & x_{n-1} \\ x_{n-1} & x_n & x_1 & \dots & x_{n-2} \\ \vdots & & & & \vdots \\ x_2 & x_3 & x_4 & \dots & x_1 \end{bmatrix} \quad (1)$$

can be written as the polynomial

$$x_1 T^n + x_2 T + x_3 T^2 \dots x_n T^{n-1}.$$

We now note that polynomials commute, so any two circulant matrices of the same order n commute.

We define the *back-diagonal matrix*, R of order n by

$$R = \begin{bmatrix} 0 & 0 & \cdots & 1 \\ 0 & 0 & \cdots & 0 \\ \vdots & & & \vdots \\ 1 & 0 & \cdots & 0 \end{bmatrix}.$$

Since $T^m R$ is the polynomial for any integer $m \geq 0$, we have that, similarly, any back-circulant matrix, of order n and first row x_1, x_2, \dots, x_n , that is,

$$\begin{bmatrix} x_1 & x_2 & x_3 & \cdots & x_n \\ x_2 & x_3 & x_4 & \cdots & x_1 \\ x_3 & x_4 & x_5 & \cdots & x_2 \\ \vdots & & & & \vdots \\ x_n & x_1 & x_2 & \cdots & x_{n-1} \end{bmatrix}$$

can be written as the polynomial

$$x_1 T^n R + x_2 T R + x_3 T^2 R \cdots x_n T^{n-1} R.$$

Mathematically we have that:

A *circulant matrix* $C = (c_{ij})$ of order n is a matrix which satisfies the condition that $c_{ij} = c_{1, j-i+1}$, where $j-i+1$ is reduced modulo n [26]. A *back circulant matrix* $B = (b_{ij})$ order n is a matrix with property that $b_{ij} = b_{1, i+j-1}$, where $i+j-1$ is reduced modulo n [26].

The transpose of a back circulant matrix is the same as itself, so it is also a symmetric matrix. In this paper we will not need to study back-circulant matrices further but define them here for completeness only.

In all our definitions of circulant and back-circulant matrices we have assumed that the rows and columns have been indexed by the order, that is for order n , the rows are named after the integers $1, 2, \dots, n$ and similarly for the columns. The internal entries are then defined by the first row using a 1:1 and onto mapping $f: G \rightarrow G$. However we could have indexed the rows and columns using the elements of a group G , with elements g_1, g_2, \dots, g_n . Loosely a *type one matrix* will then be defined so the (ij) element depends on a 1:1 and onto mapping of $f(g_j - g_i)$ for type 1 matrices and of $f(g_j + g_i)$ for *type two matrices*. We use additive notation, but that is not necessary. Seberry-Wallis and Whiteman [32] have shown that circulant and type 1 can be used interchangeably in the enunciations of theorems as can the terms back-circulant and type 2. This can be used to explore similar theorems in more structured groups.

2 Historical Background

Hadamard matrices first appeared in the literature in an 1867 paper written by J. J. Sylvester [24]. In 1892 Hadamard matrices first appear. They were called matrices

on the unit circle as they satisfied Hadamard's inequality for the determinant of matrices with entries within the unit circle [13].

Later Scarpis [20] found many Hadamard matrices using primes. In 1933 Paley [19] conjectured that Hadamard matrices existed for all positive integer orders divisible by 4. This has become known as the Hadamard conjecture:

Conjecture 1 (Paley). Hadamard matrices exist for all orders $1, 2, 4w$, where w is a positive integer.

Paley's work [19, 27] left many orders for Hadamard matrices unresolved. Later Williamson [33] gave a method that many researchers hoped would give results for all orders of Hadamard matrices. Many results are given in [1, 2, 3, 4]. That the Williamson method would give results for all orders of Hadamard matrices was first disproved by Djoković in 1993 [7].

Schmidt's review [21] of Holzmann, Kharaghani and Tayfeh-Rezaie [15] points out that there are none of order 47, 53 or 59. Unfortunately the startling paper of Holzmann, Kharaghani and Tayfeh-Rezaie [16] showed that we have no Williamson constructions for some other small orders. They give the following table:

Order:	1	3	5	7	9	11	13	15	17	19	21	23	25	27	29
Number:	1	1	1	2	3	1	4	4	4	6	7	1	10	6	1
Order:	31	33	35	37	39	41	43	45	47	49	51	53	55	57	59
Number:	2	5	0	4	1	1	2	1	0	1	2	0	1	1	0

Table 1 Number of Williamson Matrices of Order 1-59

Good matrices first appeared in the PhD Thesis of Jennifer (Seberry) Wallis [27]. There the matrices, which were given no name, were given for $w = 1, \dots, 15, 19$. In 1971 she gave good matrices for $w = 23$ [30]. The array and construction using the Seberry-Williamson array to construct skew-Hadamard matrices was also given there, but not named. Good matrices were first used by name in [29]. Hunt [17] gave the matrices for $w = 1, \dots, 25$. Later Szekeres [25] gave a list for order $w = 1, \dots, 31$. Djoković [8, 7] provided orders $w = 33, 35$ and 127. Then Georgiou, Koukouvinos and Stylianou [12] provided 37, 39. Djoković [11] says that only one set of supplementary difference sets, $(41;20,20,16,16;31)$, for 41 remains to be searched.

We note that while there are no Williamson matrices of order 35 there are good matrices of order 35.

(Seberry) Wallis [27] gave a construction for $w = 19$ and Djoković [8] for $w = 33, 35$, and 127. The remainder were found by computer search.

Other relevant publications are: [10], [6], [5],[9], [11], [22], [31].

3 Williamson Type Constructions

3.1 Williamson Array

In 1944 [33] Williamson proposed using what has come to be known as the *Williamson array*. If we can calculate suitable matrices of order w they can be plugged-in to his array to give Hadamard matrices of order $4w$.

We use the *Williamson-array* in the form

$$W_{\text{Williamson-array}} = \begin{bmatrix} A & B & C & D \\ -B & A & D & -C \\ -C & -D & A & B \\ -D & C & -B & A \end{bmatrix}$$

where A, B, C, D are circulant (cyclic) matrices with symmetric first rows which satisfy the *additive property*

$$AA^T + BB^T + CC^T + DD^T = 4wI_w. \tag{2}$$

These matrices are known as *Williamson matrices*

The Williamson-array is *formally orthogonal*. An Hadamard matrix is made by plugging *Williamson matrices* into the $W_{\text{williamson-array}}$.

Example 2. Williamson matrix of order 4×3

$$W_{12\text{Williamson}} = \begin{bmatrix} 1 & - & - & 1 & - & - & 1 & - & - & 1 & 1 & 1 \\ - & 1 & - & - & 1 & - & - & 1 & - & 1 & 1 & 1 \\ - & - & 1 & - & - & 1 & - & - & 1 & 1 & 1 & 1 \\ \hline - & 1 & 1 & 1 & - & - & 1 & 1 & 1 & - & 1 & 1 \\ 1 & - & 1 & - & 1 & - & 1 & 1 & 1 & 1 & - & 1 \\ 1 & 1 & - & - & - & 1 & 1 & 1 & 1 & 1 & 1 & - \\ \hline - & 1 & 1 & - & - & - & 1 & - & - & 1 & - & - \\ 1 & - & 1 & - & - & - & - & 1 & - & - & 1 & - \\ 1 & 1 & - & - & - & - & - & - & 1 & - & - & 1 \\ \hline - & - & - & 1 & - & - & - & 1 & 1 & 1 & 1 & - \\ - & - & - & - & 1 & - & 1 & - & 1 & - & 1 & - \\ - & - & - & - & - & 1 & 1 & 1 & - & - & - & 1 \end{bmatrix}$$

Remark 1. An example of the crucial part of proof is: when we look at the terms of $W_{\text{williamson-array}}W_{\text{williamson-array}}^T$ for, say the (2,3) element we have

$$BC^T - AD^T + DA^T - CD^T = BC - AD + DA - CB = 0.$$

Noting matrices A, B, C and D are polynomials, and commute, the (2,3) element will reduce to zero. Similarly the other off diagonal elements are 0. \square

3.2 Seberry-Williamson Array

In her PhD thesis [27] Seberry Wallis gave a Seberry-Williamson array, a modification of the Williamson array which can be used to make skew Hadamard matrices. Written in terms of circulant and back circulant matrices it is

$$W_{\text{Seberry-Williamson-array}} = \begin{bmatrix} A & BR & CR & DR \\ -BR & A & DR & -CR \\ -CR & -DR & A & BR \\ -DR & CR & -BR & A \end{bmatrix}.$$

Where A is a ± 1 skew-type cyclic matrix and B, C, D are circulant matrices with symmetric first rows which satisfy the additive property given in equation 2. These are called *good* matrices [29]. Thus the first rows each have the form

$$\sigma_A = (1)(S_A)(-S_{A^*}), \sigma_B = (1)(S_B)(S_{B^*}), \sigma_C = (1)(S_C)(S_{C^*}), \sigma_D = (1)(S_D)(S_{D^*}),$$

where S^* means the elements of S in reverse order. S_X^* are the elements of S_X reversed. (In matrix terms this is RXR .) A skew-Hadamard matrix can be made by plugging good matrices into the $W_{\text{Seberry-Williamson-array}}$.

Example 3. Seberry-Williamson matrix of order 4×3

The Seberry-Williamson matrix for first rows $A = 11-, B = 1--, C = 1--$, $D = 111$ is:

$$W_{\text{Seberry-Williamson}} = \begin{bmatrix} 1 & 1 & - & - & - & 1 & - & - & 1 & 1 & 1 & 1 & 1 & 1 \\ - & 1 & 1 & - & 1 & - & - & 1 & - & 1 & 1 & 1 & 1 & 1 \\ 1 & - & 1 & 1 & - & - & 1 & - & - & 1 & 1 & 1 & 1 & 1 \\ \hline 1 & 1 & - & 1 & 1 & - & 1 & 1 & 1 & 1 & 1 & 1 & 1 & - \\ 1 & - & 1 & - & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & - & 1 \\ - & 1 & 1 & 1 & - & 1 & 1 & 1 & 1 & - & 1 & 1 & - & 1 \\ \hline 1 & 1 & - & - & - & - & 1 & 1 & - & - & - & - & 1 & - \\ 1 & - & 1 & - & - & - & - & 1 & 1 & - & 1 & - & - & - \\ - & 1 & 1 & - & - & - & - & 1 & - & 1 & 1 & - & - & - \\ \hline - & - & - & - & - & 1 & 1 & 1 & - & 1 & 1 & - & - & - \\ - & - & - & - & 1 & - & 1 & - & 1 & - & 1 & 1 & - & - \\ - & - & - & 1 & - & - & - & 1 & 1 & 1 & 1 & - & 1 & - \end{bmatrix}.$$

3.3 Structure of First Rows of Williamson and Good Matrices

For the Williamson Hadamard matrix each of the four matrices A, B, C and D , of order w, w odd, is symmetric and thus can be written with first row

$$\sigma = 1, \underbrace{x_1, x_2, \dots, x_{\frac{w-1}{2}}}_{q \text{ negative elements}}, \underbrace{x_{\frac{w-1}{2}}, \dots, x_2, x_1}_{q \text{ negative elements}},$$

where each $x_i, i = 1, \dots, \frac{w-1}{2}$ is ± 1 .

We will refer to these first rows as

$$\sigma = \{1, S, S^*\}.$$

where, for example the first row of A ,

$$\sigma_A = \{1, S_A, S_A^*\}$$

contains

$$S_A = x_1, x_2, \dots, x_{\frac{w-1}{2}}$$

and S_A^* , the reverse of this sequence, is:

$$S_A^* = x_{\frac{w-1}{2}}, \dots, x_2, x_1.$$

Similarly we obtain $S_B, S_B^*, S_C, S_C^*, S_D$ and S_D^* . The number of such matrices, in each case, $2^{\frac{w-1}{2}}$. We see that the congruence class of S_A^* is given by the two little endian entries of S_A .

These properties will allow us to impose constraints on the search space (and time) to find these matrices.

Lemma 1. *Suppose A is a circulant matrix with first row written as $\sigma_A = (1)(S_A)(-S_A^*)$. Then the matrix A' with first row $\sigma'_A = (1)(-S_A)(S_A^*)$, that is, it has all the 2nd to w th elements of the first row written in the reverse order, has exactly the same inner products of its rows as A .*

From Marshall Hall [14, lemma 14.2.1] we have a lemma for Williamson matrices:

Lemma 2. *If w is odd, and if the Williamson matrices A, B, C, D , are chosen so the first element of their first rows is $+1$, then for each $i = 2, \dots, w$ exactly three of the i th elements of the first rows have the same sign.*

3.4 Structure of First Rows of Good Matrices

We now consider further the good matrices, A, B, C, D of order m which satisfy the additive property 2.

Write, using the shift matrix T ,

$$A = P_1 - N_1 \tag{3}$$

with P_1 the sum of the terms with positive coefficient in A and $-N_1$ the sum of the terms with negative coefficient in A , whence

$$P_1 = \sum_j a_{1j} T^{j-1}, \quad a_{1j} = +1, \quad -N = \sum_j a_{1j} T^{j-1}, \quad a_{1j} = -1 \quad (4)$$

In the same way write

$$B = P_2 - N_2, \quad C = P_3 - N_3, \quad D = P_4 - N_4. \quad (5)$$

Since $a_{11} = +1$ and A is circulant and skew-type, $a_{1j} = -a_{1,m+2-j}$, $2 \leq j \leq m$. Hence there are

$$\frac{m+1}{2} = p_1 \quad (6)$$

positive terms in the first row of A , so the number of terms in the first row of P_1 is an odd number if $m \equiv 1 \pmod{4}$ and an even number if $m \equiv 3 \pmod{4}$.

Since B is circulant and symmetric we may choose $b_{11} = +1$ and $b_{1j} = b_{1,m+2-j}$, $2 \leq j \leq m$. The positive terms occur in pairs, so p_2 the number of positive terms in the first row of P_2 , is an odd number. Similarly p_3 and p_4 are odd numbers.

We now write

$$J = I + T + T^2 + \dots + T^{m-1} = (I + T + T^2 + \dots + T^{m-1})R. \quad (7)$$

Then

$$P_i + N_i = J, \quad i = 1, 2, 3, 4 \quad (8)$$

so the additive property 2 becomes

$$AA^T + B^2 + C^2 + D^2 = 4mI_m$$

and by (3), (4) and (5) this becomes

$$(2P_1 - J)(2P_1 - J)^T + (2P_2 - J)^2 + (2P_3 - J)^2 + (2P_4 - J)^2 = 4mI_m,$$

that is

$$(2P_1 - J)(-2P_1 + J + 2I) + (2P_2 - J)^2 + (2P_3 - J)^2 + (2P_4 - J)^2 = 4mI_m,$$

since A is skew-type. So we have since $P_i J = p_i J$ and $J^2 = mJ$

$$4(-P_1^2 + P_2^2 + P_3^2 + P_4^2 + P_1) + 4(p_1 - p_2 - p_3 - p_4)J + (2m - 2)J = 4mI_m. \quad (9)$$

Now from (6)

$$4p_1 + 2m - 2 = 4m$$

so (9) becomes

$$(-P_1^2 + P_2^2 + P_3^2 + P_4^2 + P_1) = -(m - p_2 - p_3 - p_4)J + mI_m. \quad (10)$$

If m is odd, then since P_2, P_3 and P_4 all have an odd number of positive elements in their first rows, the coefficients of J are all even.

Now notice B, C, D , are polynomials in T and R so

$$P_i = \left(\sum_j e_{1j} T^{j-1} \right) R$$

for $i = 2, 3, 4$ and $e_{1j} = b_{1j}, c_{1j}, d_{1j}$ respectively, also $P_i = P_i^T$ so

$$P_i^2 = P_i P_i^T = \left(\sum_j e_{1j} T^{j-1} \right) R R^T \left(\sum_k e_{1k} T^{k-1} \right) = \sum_n f_n T^n,$$

that is P_1^2, P_2^2, P_3^2 , and P_4^2 may all be regarded as polynomials in T .

For each $t = 1, \dots, m-1$, there is a unique s such that $(T^s)^2 = T^t$. In $P_j^2 = (\sum T^k)^2$, k is a subset of $1, 2, \dots, m$, we have

$$P_j^2 \equiv \sum T^k \pmod{2}.$$

Then since the coefficient of J in (10) is always even, we have shown:

Theorem 1. *If m is odd, T the shift matrix, and P_1, P_2, P_3, P_4 are the terms with positive coefficients of A, B, C, D as defined by (8), respectively, and if*

$$AA^T + BB^T + CC^T + DD^T = 4mI$$

then writing

$$P_1 + P_1^2 = \sum_{\substack{i \\ i \neq 0}} f_i T^i \quad \text{and} \quad P_2^2 + P_3^2 + P_4^2 = \sum_{\substack{i \\ i \neq 0}} g_i T^i$$

we have $g_i = f_i \pmod{2}$ when $i \neq 0$.

Marshall Hall's lemma [14] allowed considerable improvements in algorithms to find Williamson matrices. Theorem 1 allows for improvements in algorithms to find good matrices.

3.5 Sums of Squares of First Rows for Arrays

We notice that for the arrays, of Williamson and Seberry-Williamson, which have ± 1 matrices, A, B, C, D of order w plugged into them, these must satisfy the additive property 2.

$$AA^T + BB^T + CC^T + DD^T = 4wI_w.$$

Then if \mathbf{e} is the $1 \times w$ matrix of all ones and the row sums of A, B, C, D are a, b, c , and d respectively. Then

$$\mathbf{e}A = a\mathbf{e}, \quad \mathbf{e}B = b\mathbf{e}, \quad \mathbf{e}C = c\mathbf{e}, \quad \mathbf{e}D = d\mathbf{e},$$

and

$$\mathbf{e}(AA^\top + BB^\top + CC^\top + DD^\top) = a^2\mathbf{e} + b^2\mathbf{e} + c^2\mathbf{e} + d^2\mathbf{e} = 4w\mathbf{e}.$$

For Williamson and good matrices we have

$$4w = a^2 + b^2 + c^2 + d^2.$$

Lemma 3. For the a, b, c, d , and w just defined for Williamson matrices

$$a \equiv b \equiv c \equiv d \equiv w \pmod{4}.$$

For good matrices

$$b \equiv c \equiv d \equiv w \pmod{4}. \square$$

4 Implications for Seberry-Williamson Arrays and Good Matrices

Note if

$$4w = a^2 + b^2 + c^2 + d^2, \tag{11}$$

b, c, d and w are all of the same congruence class modulo 4. a is always 1 within a good matrix.

Length	Order	Pattern of Four Squares	b, c, d	$b + c + d + w$	$ b + c + d + w$
21	84	$1^2 + 1^2 + 1^2 + d^2$	1, 1, 9	32	32
5	20	$1^2 + 1^2 + (-c)^2 + (-c)^2$	1, -3, -3	0	12
13	52	$1^2 + 1^2 + c^2 + c^2$	1, 5, 5	24	24
9	36	$1^2 + 1^2 + c^2 + d^2$	1, -3, 5	12	18
7	28	$1^2 + b^2 + b^2 + b^2$	3, 3, 3	16	16
19	76	$1^2 + (-b^2) + (-b^2) + (-b^2)$	-5, -5, -5	4	34
17	68	$1^2 + b^2 + b^2 + c^2$	-3, -3, -7	4	30
21	84	$1^2 + b^2 + c^2 + d^2$	-3, 5, -7	16	36
39	156	$1^2 + b^2 + c^2 + d^2$	-5, 7, -9	32	60

Table 2 Table of Good Matrix Observations

5 Some Observations

Lemma 4. *Squares of odd numbers are $\equiv 1 \pmod{4}$. Thus $b + c + d + w \equiv 0 \pmod{4}$.*

Lemma 5. *The only possible sum of four squares with $4w = 1^2 + (\pm 1)^2 + c^2 + c^2$ has $w \equiv c \equiv 1 \pmod{4}$ (c can be negative).*

Proof. We note that c^2 is always congruent to $\equiv 1 \pmod{4}$.

Consider the case where $4w = 1^2 + 1^2 + 2c^2$ with $c \equiv 1 \pmod{4}$, and $c = 4t + 1$, then

$$4w = 1 + 1 + 2(4t + 1)^2 = 2 + 2(16t^2 + 8t + 1) = 2 + 32t^2 + 16t + 2 = 4 + 32t^2 + 16t.$$

So $w = 1 + 8t^2 + 4t$ and $w \equiv 1 \pmod{4}$.

In the case where $4w = 1^2 + (-1)^2 + 2c^2$ with $c \equiv 3 \pmod{4}$, and $c = 4t + 3$, then

$$\begin{aligned} 4w &= 1 + 1 + 2(4t + 3)^2 = 2 + 2(16t^2 + 24t + 9) \\ &= 2 + 32t^2 + 48t + 18 = 20 + 32t^2 + 48t. \end{aligned}$$

So $w = 5 + 8t^2 + 12t$ and $w \equiv 1 \pmod{4}$. Thus c cannot be $\equiv 3 \pmod{4}$. \square

Lemma 6. *If $4w = a^2 + b^2 + c^2 + d^2$ (where a, b, c, d are all in the same congruence class as $w \pmod{4}$) then the number of ones in the first rows of $A + B + C + D$ (where A, B, C, D are good matrices) are respectively $= \frac{1+w}{2}, \frac{b+w}{2}, \frac{c+w}{2}, \frac{d+w}{2}$ and so the total number of ones in the first rows of the four good matrices is $\frac{a+b+c+d+4w}{2}$.*

6 Good Matrices and Supplementary Difference Sets

Good matrices and any other set of four ± 1 matrices which satisfy the additive property of equation (2) can be used to form supplementary difference sets (see [18]).

Example 4. In our example of Seberry-Williamson array we could have used the first rows $1 \ 1 \ - \ , \ 1 \ - \ - \ , \ 1 \ - \ - \ , \ 1 \ 1 \ 1$ for the good matrices. These correspond to sets $\{1, 2\}, \{1\}, \{1\}, \{1, 2, 3\}$ which are in fact supplementary difference sets as defined below.

Definition 1. A (v, k, λ) difference set (d_1, \dots, d_k) is a subset of v such that all the differences $d_i - d_j$, $i, j \in \{1, \dots, v-1\}$ occur precisely λ times. Note that $\lambda(v-1) = k(k-1)$.

Example 5. A $(13, 4, 1)$ difference set is $\{0, 1, 3, 9\}$ because the differences

$$\begin{array}{c|cccc} - & 0 & 1 & 3 & 9 \\ 0 & * & 1 & 3 & 9 \\ 1 & 12 & * & 2 & 8 \\ 3 & 10 & 11 & * & 6 \\ 9 & 4 & 5 & 7 & * \end{array}$$

$\{1, \dots, 12\}$ each occur once.

We use Wallis' [28] definition for $n - \{v; k_1, k_2, \dots, k_n; \lambda\}$ supplementary differences sets such that all the differences $d_i - d_j \pmod{n}$, $i, j \in \{1, \dots, k_n\}$ occur precisely λ times. Note

$$\lambda(v-1) = \sum_{i=1}^n k_i(k_i-1). \quad (12)$$

Example 6. $4 - \{9; 5, 5, 3, 7; 11\}$ supplementary difference sets (sds) are $\{1, 2, 3, 5\}$, $\{1, 3, 4, 7, 8\}$, $\{1, 2, 9\}$, $\{1, 2, 3, 5, 6, 8, 9\}$.

$$\begin{array}{c|cccc} - & 1 & 2 & 3 & 5 \\ 1 & * & 1 & 2 & 4 \\ 2 & 8 & * & 1 & 3 \\ 3 & 7 & 8 & * & 2 \\ 5 & 5 & 6 & 7 & * \end{array} \quad \begin{array}{c|cccc} - & 1 & 3 & 4 & 7 & 8 \\ 1 & * & 2 & 3 & 6 & 7 \\ 3 & 7 & * & 1 & 4 & 5 \\ 4 & 6 & 8 & * & 3 & 4 \\ 7 & 3 & 5 & 6 & * & 1 \\ 8 & 2 & 4 & 5 & 8 & * \end{array} \quad \begin{array}{c|ccc} - & 1 & 2 & 9 \\ 1 & * & 1 & 8 \\ 2 & 8 & * & 7 \\ 9 & 1 & 2 & * \end{array} \quad \begin{array}{c|cccccc} - & 1 & 2 & 3 & 5 & 6 & 8 & 9 \\ 1 & * & 1 & 2 & 4 & 5 & 7 & 8 \\ 2 & 8 & * & 1 & 3 & 4 & 6 & 7 \\ 3 & 7 & 8 & * & 2 & 3 & 5 & 6 \\ 5 & 5 & 6 & 7 & * & 1 & 3 & 4 \\ 6 & 4 & 5 & 6 & 8 & * & 2 & 7 \\ 8 & 2 & 3 & 4 & 6 & 7 & * & 1 \\ 9 & 1 & 2 & 3 & 5 & 2 & 8 & * \end{array}$$

We note that (12) becomes

$$11(9-1) = 88 = 20 + 20 + 6 + 42.$$

We now give the relationship between the necessary condition for good matrices from (11)

$$4w = a^2 (= 1^2) + b^2 + c^2 + d^2$$

and $G = \{w; k, k_2, k_3, k_4; \lambda\}$ sds.

Lemma 7. *Let w be the order of 4 good matrices. Then, with*

$$4w = a^2 + b^2 + c^2 + d^2$$

where $a = 1$ and w, b, c, d all in the same congruence class modulo 4 the good matrices correspond to

$$4 - \left\{ w; \frac{a+w}{2}, \frac{b+w}{2}, \frac{c+w}{2}, \frac{d+w}{2}; w + \frac{a+b+c+d}{2} \right\} \quad (13)$$

supplementary difference sets.

Proof. We write the positions of 1s in the first rows of the good matrices as subsets of w of size k_1, k_2, k_3, k_4 then using p for the number of positive elements and q for the number of negative elements in each sds, $i = 2, 3, 4$ we have

$$p + q = w \quad (14)$$

and

$$p_2 - q_2 = b, \quad p_3 - q_3 = c \quad \text{and} \quad p_4 - q_4 = d. \quad (15)$$

Thus, $2p_2 = w + b$, $2p_3 = w + c$, $2p_4 = w + d$ as $k_2 = \frac{1}{2}(w + b)$, $k_3 = \frac{1}{2}(w + c)$ and $k_4 = \frac{1}{2}(w + d)$. Since $a = 1$ and the first good matrix is skew-type $k_1 = \frac{1}{2}(w + a)$.

Now for sds $4 - \{w; k_1, k_2, k_3, k_4; \lambda\}$ we have

$$\lambda(v - 1) = \sum_{i=1}^n k_i(k_i - 1)$$

and

$$\begin{aligned} \lambda(w - 1) &= \left(\frac{a+w}{2}\right) \left(\frac{a+w-2}{2}\right) + \left(\frac{b+w}{2}\right) \left(\frac{b+w-2}{2}\right) \\ &\quad + \left(\frac{c+w}{2}\right) \left(\frac{c+w-2}{2}\right) + \left(\frac{d+w}{2}\right) \left(\frac{d+w-2}{2}\right) \quad (16) \end{aligned}$$

$$\begin{aligned} &= \frac{1}{4} (a^2 + w^2 + 2aw - 2w - 2a + b^2 + w^2 + 2bw - 2w - 2b + c^2 + w^2 \\ &\quad + (cbw - 2w - 2c + d^2 + w^2 + 2dw - 2w - 2d) \end{aligned}$$

$$= \frac{1}{4} (a^2 + b^2 + c^2 + d^2 - 2(w-1)(a+b+c+d) + 4w^2 - 8w)$$

$$= \frac{1}{4} (4w^2 - 4w - 2(w-1)(a+b+c+d))$$

$$= w(w-1) + \frac{1}{2}(w-1)(a+b+c+d)$$

and so

$$\lambda = w + \frac{a+b+c+d}{2}. \quad (17)$$

Thus we have the result. \square

Example 7. For $w = 9$, we have seen, above $4 - \{9; 5, 5, 3, 1; 11\}$ sds and $4w = 36 = a^2 (= 1^2) + b^2 (= 1^2) + c^2 (= (-3)^2) + d^2 (= 5^2)$.

We have for $w = 9$, $k_1 = \frac{1}{2}(9+1)$, $k_2 = \frac{1}{2}(9+1)$, $k_3 = \frac{1}{2}(9-3)$, $k_4 = \frac{1}{2}(9+5)$

and $\lambda = w + \frac{1}{2}(a + b + c + d) = 9 + \frac{1}{2}(1 + 1 - 3 + 5) = 9 + 2 = 11$. Thus we have $4 - \{9; 5, 5, 3, 7; 11\}$ sds.

Remark 2. Lemma 7 actually applies to any four circulant matrices with elements of ± 1 which have row sums $|a|, |b|, |c|, |d|$ which satisfy the additive property given in equation 2.

7 Conclusion

We have given for the first time conditions to improve computer searches for good matrices and hence for skew-Hadamard matrices. Further research will be undertaken to implement this on various platforms.

This survey has not been submitted to any other book or journal.

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